

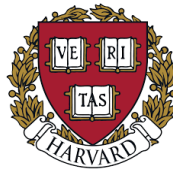
Analytic Regression and the Semi-numerical Landau Bootstrap



Symbology@15

Dec 17, 2025

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Institute for Artificial Intelligence
and Fundamental Interactions (IAIFI)

Based on

“Applications of the Landau Bootstrap” [2410.02424](#)

“Constraints on sequential discontinuities from the geometry of on-shell spaces” [2211.07633](#)

- By H. Hannesdottir, A. McLeod, MDS, C. Vergu

“Analytic Regression of Feynman Integrals from High-Precision Numerical Sampling”, [2507.17815](#)

- By O. Barrera, A. Dersy, R. Husain, MDS and X. Zhang

Outline

1. Landau bootstrap



Easy



Hard

Constraints	# Coeffs
All Symbols	20736
Integrability	6993
Galois symmetry	861
Physical branch cuts	161
Genealogical constraints	28
α -positive thresholds	6

Hard



Easy

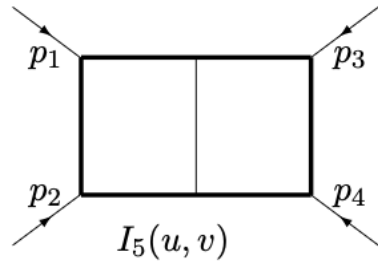


2. Analytic regression with lattice reduction

Bootstrapping integrals

Q: Can we bootstrap Feynman integrals?

Rules: Don't integrate!



$$I_5(u, v) = \int \frac{d^D k_1}{(2\pi)^D} \int \frac{d^D k_2}{(2\pi)^D} \frac{1}{[k_1^2 + m^2] [k_2^2 + m^2] [(k_1 - p_1)^2 + m^2] [(k_2 - p_3)^2 + m^2] [(k_1 - k_2)^2]}$$

- Computed by Caron-Huot and Henn 1404.2922

$$\begin{aligned} g_{10} = & G_{-1,0} H_{-1,-1} + G_{-1,\frac{1}{2},\frac{1}{2}} H_{-1,-1} - G_{-1,-\frac{1}{2},\frac{1}{2}} H_{-1,-1} + 2G_{0,-1} H_{-1,-1} + G_{0,0} H_{-1,-1} \\ & - 2G_{0,\frac{1}{2}} H_{-1,-1} - G_{0,\frac{1}{2},\frac{1}{2}} H_{-1,-1} - G_{0,-\frac{1}{2},\frac{1}{2}} H_{-1,-1} - G_{1,0} H_{-1,-1} - G_{1,\frac{1}{2},\frac{1}{2}} H_{-1,-1} \\ & + G_{1,-\frac{1}{2},\frac{1}{2}} H_{-1,-1} + G_{-1,0} H_{-1,0} - G_{-1,\frac{1}{2},\frac{1}{2}} H_{-1,0} - G_{-1,-\frac{1}{2},\frac{1}{2}} H_{-1,0} + G_{0,\frac{1}{2},\frac{1}{2}} H_{-1,0} \\ & - G_{0,-\frac{1}{2},\frac{1}{2}} H_{-1,0} - G_{1,0} H_{-1,0} + G_{1,\frac{1}{2},\frac{1}{2}} H_{-1,0} + G_{1,-\frac{1}{2},\frac{1}{2}} H_{-1,0} + G_{-1,0} H_{-1,1} + G_{-1,\frac{1}{2},\frac{1}{2}} H_{-1,1} \\ & - G_{-1,-\frac{1}{2},\frac{1}{2}} H_{-1,1} + 2G_{0,-1} H_{-1,1} + G_{0,0} H_{-1,1} - 2G_{0,\frac{1}{2}} H_{-1,1} - G_{0,\frac{1}{2},\frac{1}{2}} H_{-1,1} - G_{0,-\frac{1}{2},\frac{1}{2}} H_{-1,1} \\ & - G_{1,0} H_{-1,1} - G_{1,\frac{1}{2},\frac{1}{2}} H_{-1,1} + G_{1,-\frac{1}{2},\frac{1}{2}} H_{-1,1} - G_{-1,0} H_{0,-1} + G_{-1,\frac{1}{2},\frac{1}{2}} H_{0,-1} + G_{-1,-\frac{1}{2},\frac{1}{2}} H_{0,-1} \\ & - G_{0,\frac{1}{2},\frac{1}{2}} H_{0,-1} + G_{0,-\frac{1}{2},\frac{1}{2}} H_{0,-1} + G_{1,0} H_{0,-1} - G_{1,\frac{1}{2},\frac{1}{2}} H_{0,-1} - G_{1,-\frac{1}{2},\frac{1}{2}} H_{0,-1} + G_{-1,0} H_{0,0} \\ & - G_{-1,\frac{1}{2},\frac{1}{2}} H_{0,0} + G_{-1,-\frac{1}{2},\frac{1}{2}} H_{0,0} + G_{0,1} H_{0,0} - G_{0,\frac{1}{2},\frac{1}{2}} H_{0,0} - G_{0,-\frac{1}{2},\frac{1}{2}} H_{0,0} - G_{1,\frac{1}{2},\frac{1}{2}} H_{0,0} \\ & + G_{1,-\frac{1}{2},\frac{1}{2}} H_{0,0} - G_{-1,0} H_{0,1} + G_{-1,\frac{1}{2},\frac{1}{2}} H_{0,1} + G_{-1,-\frac{1}{2},\frac{1}{2}} H_{0,1} - G_{0,\frac{1}{2},\frac{1}{2}} H_{0,1} + G_{0,-\frac{1}{2},\frac{1}{2}} H_{0,1} \\ & + G_{1,0} H_{0,1} - G_{1,\frac{1}{2},\frac{1}{2}} H_{0,1} - G_{1,-\frac{1}{2},\frac{1}{2}} H_{0,1} - G_{-1,0} H_{1,-1} + G_{-1,\frac{1}{2},\frac{1}{2}} H_{1,-1} - G_{-1,-\frac{1}{2},\frac{1}{2}} H_{1,-1} \\ & + G_{0,0} H_{1,-1} + 2G_{0,\frac{1}{2}} H_{1,-1} - 2G_{0,\frac{1}{2},\frac{1}{2}} H_{1,-1} - G_{0,\frac{1}{2},\frac{1}{2}} H_{1,-1} - G_{0,-\frac{1}{2},\frac{1}{2}} H_{1,-1} + G_{1,0} H_{1,-1} \\ & - G_{1,\frac{1}{2},\frac{1}{2}} H_{1,-1} + G_{1,-\frac{1}{2},\frac{1}{2}} H_{1,-1} + G_{-1,0} H_{1,0} - G_{-1,\frac{1}{2},\frac{1}{2}} H_{1,0} - G_{-1,-\frac{1}{2},\frac{1}{2}} H_{1,0} + G_{0,\frac{1}{2},\frac{1}{2}} H_{1,0} \\ & - G_{0,-\frac{1}{2},\frac{1}{2}} H_{1,0} - G_{1,0} H_{1,0} + G_{1,\frac{1}{2},\frac{1}{2}} H_{1,0} + G_{1,-\frac{1}{2},\frac{1}{2}} H_{1,0} - G_{-1,0} H_{1,1} + G_{-1,\frac{1}{2},\frac{1}{2}} H_{1,1} \\ & - G_{-1,-\frac{1}{2},\frac{1}{2}} H_{1,1} + G_{0,0} H_{1,1} + 2G_{0,\frac{1}{2}} H_{1,1} - 2G_{0,\frac{1}{2},\frac{1}{2}} H_{1,1} - G_{0,\frac{1}{2},\frac{1}{2}} H_{1,1} - G_{0,-\frac{1}{2},\frac{1}{2}} H_{1,1} \end{aligned}$$

1. Parametrize a finite basis

$$I_5(s, t, u, m) = \sum_{j=1}^{\text{finite}} c_j f_j(s, t, u, m)$$

- determined by singularities

2. Landau bootstrap

apply enough constraints to uniquely fix all c_j

3. Analytic regression

fit the c_j numerically

Landau Equations

$$I_G(p) = (n_{\text{int}} - 1)! \int_0^\infty \prod_{e \in E_{\text{int}}(G)} d\alpha_e \int \prod_{c \in \hat{C}(G)} d^d k_c \frac{1}{(\ell + i\varepsilon)^{n_{\text{int}}}} \delta\left(1 - \sum_{e \in E_{\text{int}}(G)} \alpha_e\right)$$

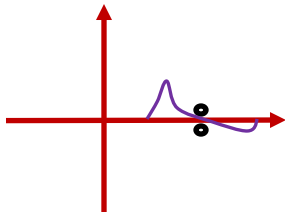
A necessary condition for a singularity is that the *integrand* is singular ($\ell=0$)

$$\ell = \sum_{e \in E_{\text{int}}(G)} \alpha_e (q_e^2 - m_e^2) = 0$$

- every internal line is either on-shell ($q^2=m^2$) or $\alpha=0$ or both

A necessary condition for a singularity of the *integral* is that poles pinch the contour

Double pole:



integration contour
pinched between poles

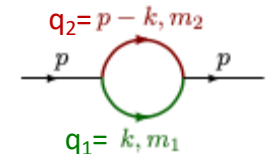
for each loop k_c :

$$\sum_{e \in E_{\text{int}}(G^k)} \alpha_e \frac{\partial}{\partial k_c} (q_e^2 - m_e^2) = 0.$$

- since q_e are linear in k_c

$$\sum_{e \text{ in loop}} \pm \alpha_e q_e^\mu = 0$$

Landau loop equations



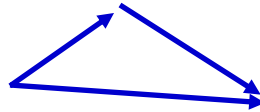
Coleman-Norton interpretation

Landau equations

$$\ell = \sum_{e \in E_{\text{int}}(G)} \alpha_e (q_e^2 - m_e^2) = 0$$

$$\sum_{e \text{ in loop}} \pm \alpha_e q_e^\mu = 0$$

4-momenta add up to zero after rescaling by α



[Coleman and Norton 1965]

Landau diagram is interpreted as space-time diagram

- momenta are on-shell (classical)
- α_e are the proper times for propagation

More physically: singularities due to classically allowed processes

- similar to optical theorem

Pham interpretation

Landau equations

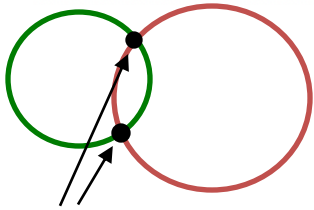
$$\ell = \sum_{e \in E_{\text{int}}(G)} \alpha_e (q_e^2 - m_e^2) = 0$$

$$\sum_{e \text{ in loop}} \pm \alpha_e q_e^\mu = 0$$

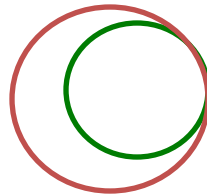
normal vectors
of on-shell constraints $q^2=m^2$
are linearly dependent

on-shell constraints (Euclidean $d=2$)

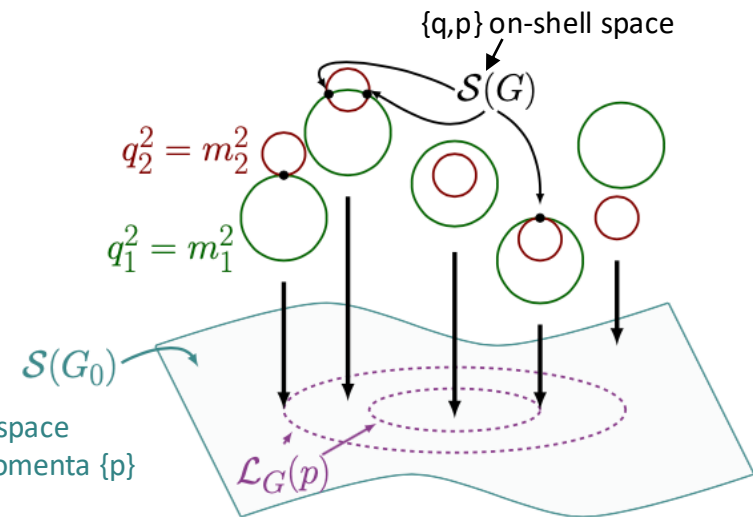
$$q_x^2 + q_y^2 = m_e^2$$



intersection
satisfies both
on-shell constraints

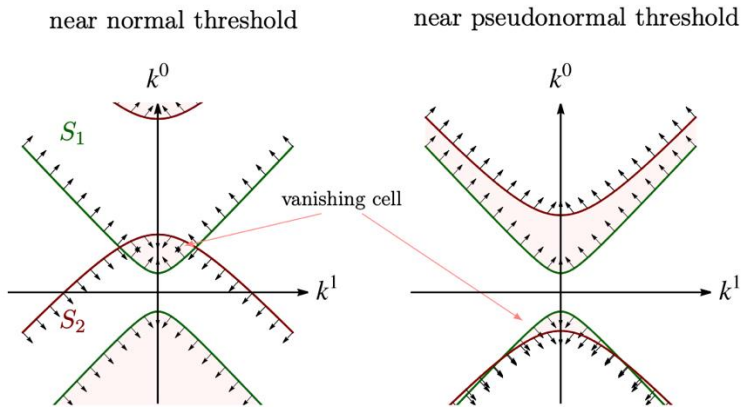


tangent on boundary
of space where
circles intersect



Different kinds of singularities

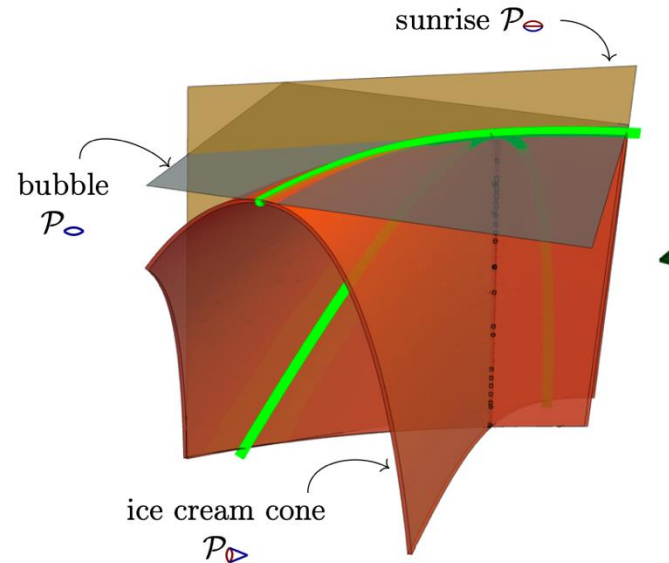
Simple pinches



- hypersurfaces meet transversely
- e.g. physical thresholds

McLeod, Hannesdottir, MDS, Vergu
arXiv:2211.07633

Non-simple pinches



- hypersurfaces meet tangentially
 - e.g. sunrise in the ice-cream cone

$$G_{\triangleright} = \text{diagram with external lines } q_1, q_2, q_3, q_4 \text{ and internal lines } q_1, q_2, q_3 \text{ meeting at a point} \xrightarrow{\bar{\kappa}} G_{\circ} = \text{diagram with external lines } q_1, q_2, q_3, q_4 \text{ and internal lines } q_1, q_2 \text{ meeting at a point}$$

- Permanent pinches (e.g. IR divergences)
- Pinches at infinity

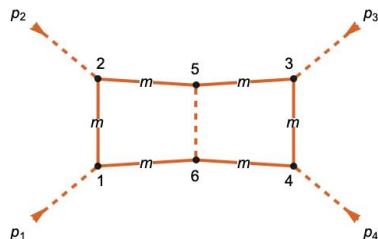
Solving the Landau equations

Lots of ways to solve the Landau equations

- Solve them by hand (e.g. Eden et al 1950)
- HyperInt (Panzer 2014)
- PLD (Fevola, Mizera, Telen 2013)
- BaikovLetter (Jiang et al 2024)
- Recursive approach (Caron-Huot, M. Correia and M. Giroux 2024)
- Numerical implementation for any diagram (Correia, Giroux, Mizera 2024) **SOFIA**

Input

```
diag =
  {{{{1, 2}, m1}, {{2, 5}, m2}, {{3, 5}, m3}, {{3, 4}, m4}, {{4, 6}, m5},
    {{1, 6}, m6}, {{5, 6}, m7}}, {{1, M1}, {2, M2}, {3, M3}, {4, M4}}} /.
  m7 -> 0 /. m- -> m /. M- -> 0
FeynmanPlot[diag]
```



Output

```
] := candidateSingularities =
  SOFIA[diag, SolverBound -> Infinity];
% // TableForm
```

Total runtime= 2.86441

```

mm
s12
s23
s12 + s23
mm - s12
mm - s23
4 mm - s12
4 mm - s23
4 mm s12 + 4 mm s23 - s12 s23
mm2 s12 - 2 mm s12 s23 - 4 mm s232 + s12 s232
mm s122 + 4 mm s12 s23 - s122 s23 + 4 mm s232 - s12 s232

```

Finds all
singularities
(simple & non-simple)

Finite basis

Alphabet = {letters}

- A letter L can appear in the symbol
- Integral can **only** have singularities when $L=0$

$$\mathcal{S}[\mathcal{I}] = L_{i_1} \otimes \dots \otimes L_{i_n}$$



Landau's original paper determined if singularities were logarithmic or square-root

- Not so easy to use, since singularities may appear multiple times on multiple sheets
- Still true that singularities are always either **logarithmic** or **square root**

singularities

$\{s, t, s-t\}$



alphabet

$$\left\{ s, t, s-t, \frac{\sqrt{s-t} - \sqrt{s}}{\sqrt{s-t} + \sqrt{s}} \right\}$$

$$\left\{ s=0, \frac{1}{s}=0 \right\}$$

logarithmic

$$\left\{ s=0, \frac{1}{t}=0, s=t, t, \frac{1}{s} \right\}$$

logarithmic square root

- Galois symmetry
 - invariance under $i \rightarrow -i$
 - or $\sqrt{\cdot} \rightarrow -\sqrt{\cdot}$
 - $\sqrt{s-t}$ not a valid letter

Finite basis

Location of Landau singularities

$$\begin{aligned} s &= 4m^2, & s &\rightarrow \infty, \\ t &= 4m^2, & t &\rightarrow \infty, \\ m^2 &= 0, \\ s &= 0, & t &= 0, & m^2 &\rightarrow \infty, \\ s+t &= 0, & st-4m^2s-4m^2t &= 0. \end{aligned}$$



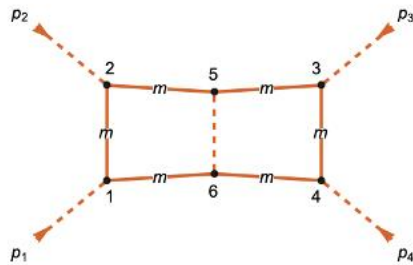
symbol alphabet

$$\tilde{A} = \left\{ u, v, 1+u, 1+v, u+v, 1+u+v, \frac{\beta_u - 1}{\beta_u + 1}, \frac{\beta_v - 1}{\beta_v + 1}, \frac{\beta_{uv} - 1}{\beta_{uv} + 1}, \frac{\beta_{uv} - \beta_u}{\beta_{uv} + \beta_u}, \frac{\beta_{uv} - \beta_v}{\beta_{uv} + \beta_v}, \frac{\beta_{uv} - \beta_u\beta_v}{\beta_{uv} + \beta_u\beta_v} \right\}$$

$$\beta_u = \sqrt{1+u}, \quad \beta_v = \sqrt{1+v}, \quad \beta_{uv} = \sqrt{1+u+v}.$$

- SOFIA can also produce the alphabet (may be larger than needed)

- Length of symbol is $\leq 2 \times$ loop order



- 12 letters
- $12^4 = 20,736$ **symbol** entries

$$\mathcal{S}[\mathcal{I}] = \sum c_{\{i\}} L_{i_1} \otimes L_{i_2} \otimes L_{i_3} \otimes L_{i_4}$$

Finite basis!

2 loop outer-mass double box



Landau Bootstrap

$$\mathcal{S}[\mathcal{I}] = \sum c_{\{i\}} L_{i_1} \otimes L_{i_2} \otimes L_{i_3} \otimes L_{i_4}$$

How can we fix the coefficients?

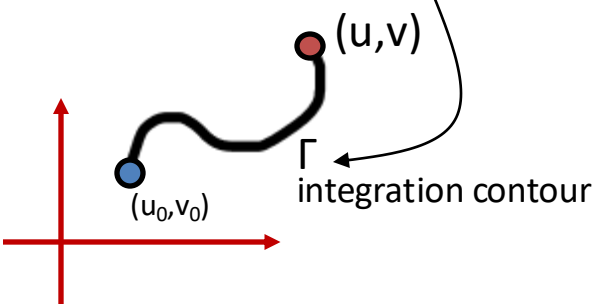
- Integrability
- Galois symmetry
- α -positivity
- First-entry conditions
- Last-entry conditions
- Genealogical constraints
 - Sequential discontinuities
 - Cluster adjacency conditions
- Regions analysis
 - Soft, collinear, Regge limits
 - Often don't work diagram-by-diagram
- Direct calculation

Sequences of four letters	20736
Integrable weight-four symbols	6993
Galois symmetry	861
Physical logarithmic branch cuts	161
Genealogical constraints	28
Only algebraic α -positive thresholds	6
Threshold expansion in t	1


Integrability

- Every iterated dlog integral has a symbol

$$f(u, v; \Gamma) = c_{i_1, i_2, \dots, i_n} \int_{\Gamma} d \ln L_{i_1} \circ \dots \circ d \ln L_{i_n} \xrightarrow{\text{green}} \sum c_{i_1, i_2, \dots, i_n} L_{i_1} \otimes \dots \otimes L_{i_n}$$



- Not every symbol corresponds to a function



- For $f(u, v; \Gamma)$ to be a function, must be independent of local path deformations

$$\Rightarrow [\partial_u, \partial_v] f = 0$$

- Derivatives only act on the last entry of the symbol (end of integration contour)

$$\partial_u [S \otimes K \otimes L] = (\partial_u \ln L) [S \otimes K]$$

$$\partial_v \partial_u [S \otimes K \otimes L] = (\partial_v \partial_u \ln L) [S \otimes K] + (\partial_u \ln L) (\partial_v \ln K) S$$

$$[\partial_u, \partial_v] [S \otimes K \otimes L] = [(\partial_u \ln L) (\partial_v \ln K) - (\partial_v \ln K) (\partial_u \ln L)] S$$

must vanish
(integrability condition)

α positivity

- Symbol encodes all branch points, even on **unphysical sheets**

$$I_G(p) = (n_{\text{int}} - 1)! \int_0^\infty \prod_{e \in E_{\text{int}}(G)} d\alpha_e \int \prod_{c \in \widehat{C}(G)} d^d k_c \frac{1}{(\ell + i\varepsilon)^{n_{\text{int}}}} \delta\left(1 - \sum_{e \in E_{\text{int}}(G)} \alpha_e\right)$$

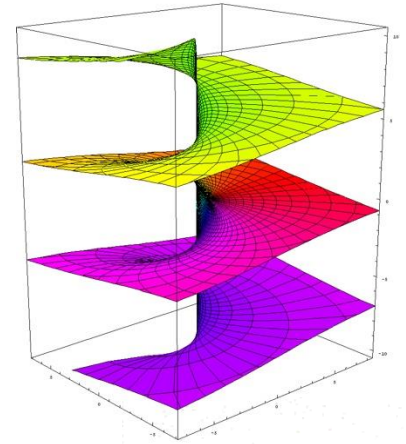
actual Feynman integral on physical sheet is over positive α

- Discontinuities/monodromies act on first entry of the symbol

$$I = \int \omega_1 \int \omega_2 \dots \int \omega_n$$

$$dI = \omega_1 \int \omega_2 \dots \int \omega_n$$

- Singularity for physical momenta (physical sheet) \leftrightarrow singularity of first entry
 - See if $\alpha > 0$ in solutions to Landau equations: constrain first symbol entries

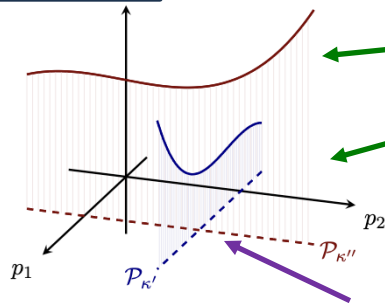


Genealogical constraints

Which symbol entries can be adjacent?

- Adjacent means sequential discontinuities are possible

Pham approach

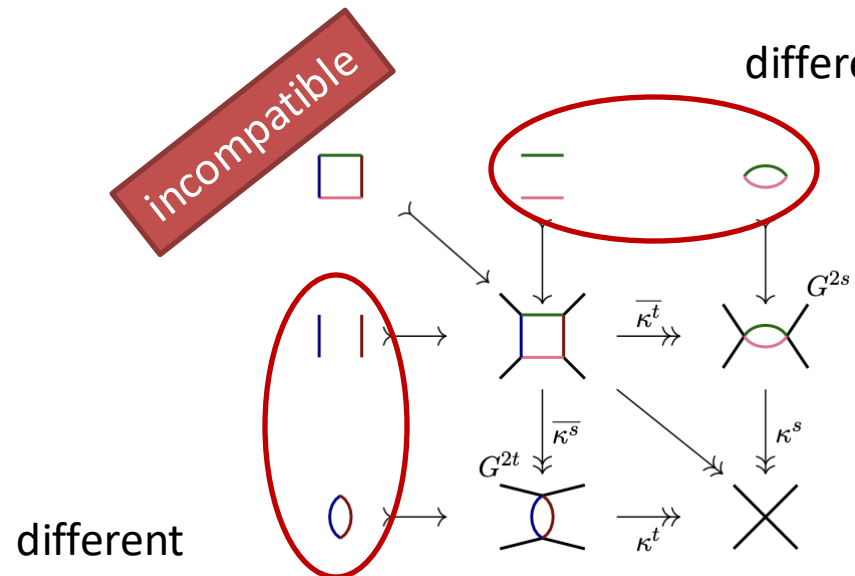
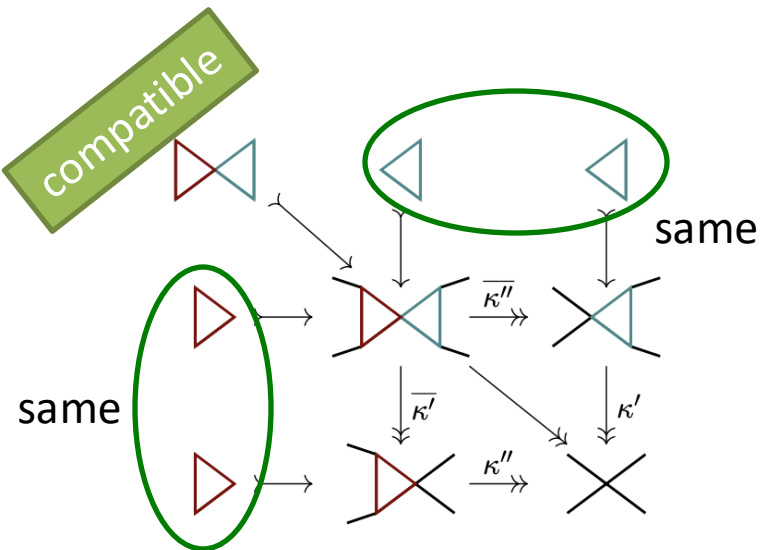


on-shell surfaces may not intersect in *internal momenta*

- vanishing cell from first monodromy doesn't intersect integration contour of second
- sequential monodromy vanishes

$$(1 - \mathcal{M}_{\mathcal{P}_{\kappa'}})(1 - \mathcal{M}_{\mathcal{P}_{\kappa''}})I_G(p) = 0$$

Singular surfaces intersect transversally in *external momenta*



- e.g. Steinmann relations

Outer-mass double box

Landau bootstrap

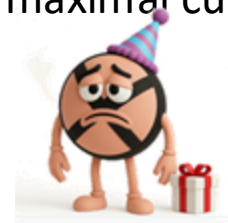
Easy

Constraints # Coeffs

All Symbols	20736
Integrability	6993
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α -positive thresholds	6

Hard

- Impose as many constraints as you can
- Work from easy generic stuff (integrability) to hard
- Also need **rational prefactor**
 - SOFIA can compute prefactor from maximal cut
 - **Not part of the symbol**
- Final steps may involve computing integral in a limit



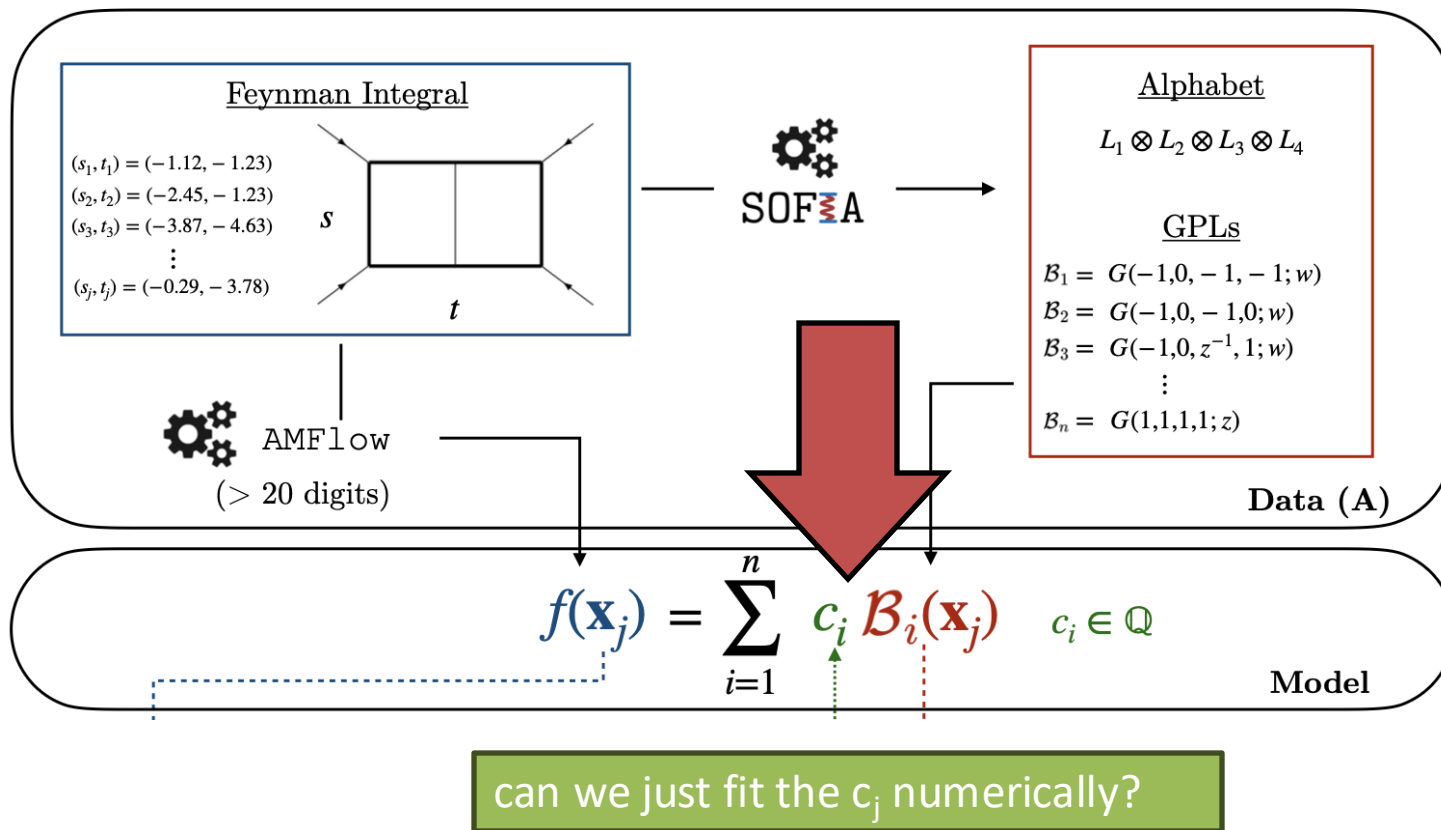
- **Landau bootstrap works!**

$$\begin{aligned}
 \mathcal{S}(\tilde{\mathcal{I}}_{\text{dbox}}) = & -L_6 \otimes \frac{L_1}{L_3} \otimes L_6 \otimes L_9 - L_6 \otimes \frac{L_1}{L_3} \otimes L_9 \otimes L_6 \\
 & + L_6 \otimes L_6 \otimes \frac{L_1 L_2}{L_3 L_5} \otimes L_9 + L_6 \otimes L_9 \otimes \frac{L_2}{L_5} \otimes L_6 \\
 & + L_6 \otimes L_6 \otimes L_8 \otimes L_6 + L_6 \otimes L_9 \otimes L_8 \otimes L_9 \\
 & + L_7 \otimes L_{10} \otimes \frac{L_2}{L_5} \otimes L_6 + L_7 \otimes L_{10} \otimes L_8 \otimes L_9 \\
 & + L_7 \otimes L_7 \otimes \frac{L_1}{L_5} \otimes L_9 + L_7 \otimes L_7 \otimes L_8 \otimes L_6 .
 \end{aligned}$$



- Agrees with Caron-Huot & Henn '14

Numerical bootstrap

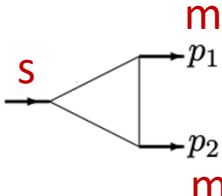


Start with finite basis

Requirements

1. Evaluate $f(x)$ numerically to high precision
2. Evaluate $B(x)$ to high precision
3. Solve the equation without losing precision

1-loop triangle

exact answer: $T =$  $= \frac{x}{m^2(1-x^2)} \left(-\frac{\pi^2}{3} + 4G(0, -1, x) - 2G(0, 0; x) \right)$

one invariant $x = \frac{1 - \sqrt{1 + \frac{4m^2}{s}}}{1 + \sqrt{1 + \frac{4m^2}{s}}}$

Alphabet (from Sofia)

3 letters

$$A = \{L\} = \{m, s, 4m^2 - s\} \longleftrightarrow \{x, 1+x, 1-x\}$$

rational
prefactor

(Sofia computes)

Total runtime= 0.042703

$$-\frac{1}{16 \pi^4 \sqrt{(4 m^2 - s) s}}$$

Basis is

$$T(x) = \sum_{i=1}^{17} c_i \mathcal{B}_i(x) = P(x) \times \underbrace{[c_{ij} L_i \otimes L_j]}_{\substack{9 \text{ terms} \\ \text{weight } 2}} + \underbrace{(a_j + b_j \pi) L_j}_{\substack{6 \text{ terms} \\ \text{weight } 1}} + \underbrace{d_1 \pi^2 + d_2 \zeta_3}_{\substack{2 \text{ numbers}}}$$

17
constants

- Need $T(x)$ and $\mathcal{B}_i(x)$ to high precision

Numerical Feynman Integration

- AMFlow: numerical evaluation for Feynman loop integrals to high precision

Integration-by-Parts (IBP) [Chetyrkin, Tkachov, 1981]

$$\mathcal{I}(p_i, m_e) = \int \prod_{j=1}^L d^D k_j \frac{N(p_i, k_j)}{\prod_{e=1}^E (q_e^2 - m_e^2 + i\varepsilon)} \Rightarrow \mathcal{I} = \sum_a \overbrace{R_a(p_i \cdot p_j, m_e)}^{\text{Rational functions}} \overbrace{\text{MI}_a}^{\text{Master integrals (basis)}}$$

Auxiliary mass flow method (AMFlow)

[Liu, Ma, 1801.10523; 2107.01864;
2201.11669; 2201.11637]

1. Introduce an auxiliary mass η to some of the propagator denominators
2. Set up closed differential equations w.r.t η using IBPs
3. Solve the differential equations numerically with boundary conditions $\eta \rightarrow \infty$

Timing on 1-loop triangle

- each phase space point takes 5-10 CPU-min for 30 significant digits

Numerical basis functions

$$T(x) = \sum_{i=1}^{17} c_i \mathcal{B}_i(x) = P(x) \times [c_{ij} L_i \otimes L_j + (a_j + b_j \pi) L_j + d_1 \pi^2 + d_2 \zeta_3]$$

- Rational prefactor evaluation is instant
- Weight-2 symbols can be integrated into closed form expressions
 - FiberSymbol in Polylogtools can do this
 - Numerical evaluation is very fast



Integrals of higher weight symbols are not always known

- Can always integrate numerically along a path

$$\tilde{B} = \sum_{i=1}^{|\tilde{A}|} c_{i_1, i_2, i_3, i_4} \int_0^1 d \log L_{i_4}(\lambda_4) \int_0^{\lambda_4} d \log L_{i_3}(\lambda_3) \int_0^{\lambda_3} d \log L_{i_2}(\lambda_2) \int_0^{\lambda_2} d \log L_{i_1}(\lambda_1),$$

- Individual terms may be path dependent, but final result is integrable
- Can do the first and last integral analytically
 - Reduce weight by 2: speeds up integration tremendously
- Sometimes analytic integrals can be so complicated that it is faster to do the integral numerically
 - More work needed on efficient numerical evaluation

Matrix inversion

- Evaluate both sides of this equation at **17 points**
- **Solve 17 linear equations** for coefficients
 - i.e. invert the matrix

$$T(x) = \sum_{i=1}^{17} c_i \mathcal{B}_i(x)$$

$$M_{ij} = \mathcal{B}_i(\mathbf{x}_j) \quad \Rightarrow \quad c_i = (M^{-1})_{ij} \cdot T(x_j)$$

Problems:

1. No way to impose that **c_j are rational**
 - Cannot even resolve functions that differ by irrational constants

$$2 [\ln x] + 3 [\pi \ln x] = (1 + \pi) [\ln x] + \left(2 + \frac{1}{\pi}\right) [\pi \ln x]$$

- Even with infinite precision, will not find the exact analytic answer

2. **Matrix inversion loses precision very fast**

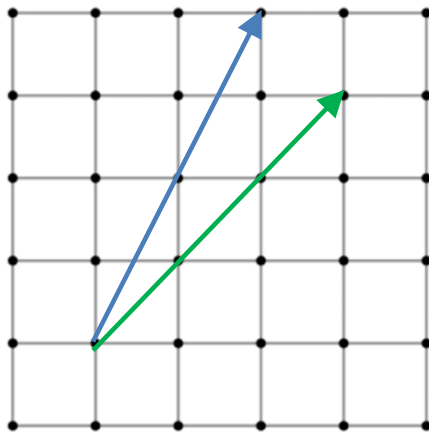
- Controlled by condition number

$$\kappa(M) = \|M\| \|M^{-1}\|.$$

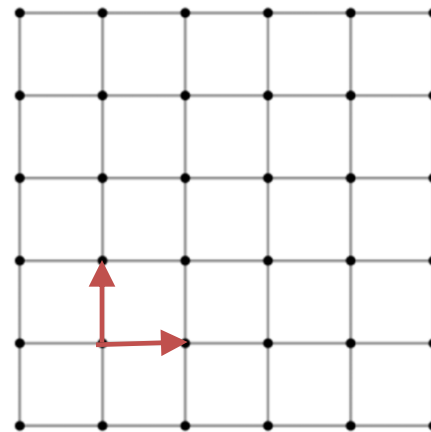
- Generally our matrices will be ill-conditioned
(they come from smooth functions)

Lattice reduction

vectors span
a lattice



$$\vec{u}_1^2 + \vec{u}_2^2 = 24$$



$$\vec{v}_1^2 + \vec{v}_2^2 = 2$$

- Lattice reduction finds another set of vectors for same lattice
- Can minimize some norm (length of lattice vectors)
- NP-Hard problem: no polynomial-time algorithm for truly best solution
- Efficient algorithms exist to find what is almost always the minimum

Lattice reduction

Rational number coefficients can be fit for numbers using lattice reduction

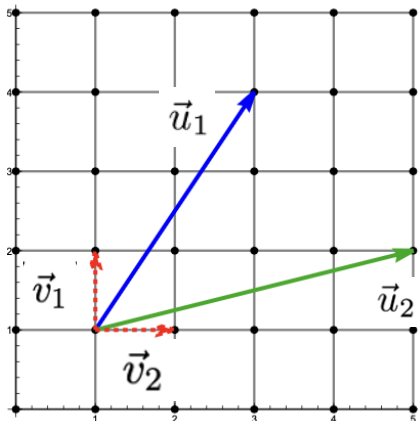
$$f = - \int_0^1 du \int_0^1 dv \frac{\log(1-uv) + v \log(1-u)}{uv} = \frac{\pi^2}{6} + \zeta_3 = c_1 \pi^2 + c_2 \zeta_3 = \vec{c} \cdot \vec{v}$$

$$f=2.847 \longleftrightarrow \text{Assume 4 digits known} \longleftrightarrow \pi^2=9.870 \quad \zeta_3=1.202$$

Multiply by 10^3 and put into a matrix

$$\begin{pmatrix} \vec{u}_1 \\ \vec{u}_2 \\ \vec{u}_3 \end{pmatrix} = \begin{pmatrix} 10^3 f & 1 & & \\ 10^3 \pi^2 & & 1 & \\ 10^3 \zeta_3 & & & 1 \end{pmatrix} = \begin{pmatrix} 2847 & 1 & 0 & 0 \\ 9870 & 0 & 1 & 0 \\ 1202 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{\text{lattice reduction}} \begin{pmatrix} \vec{v}_1 \\ \vec{v}_2 \\ \vec{v}_3 \end{pmatrix} = \begin{pmatrix} 0 & -6 & 1 & 6 \\ 3 & -11 & 5 & -15 \\ 62 & 4 & -2 & 7 \end{pmatrix}$$

vectors span
a lattice



- Lattices are the same so v in the span of u

$$\vec{v}_1 = -6\vec{u}_1 + \vec{u}_2 + 6\vec{u}_3.$$

First component

$$0 = 10^3 \times (-6f + \pi^2 + 6\zeta^3) \quad \checkmark$$

Precision requirements

Rational number coefficients can be fit for numbers lattice reduction

$$f = - \int_0^1 du \int_0^1 dv \frac{\log(1 - uv) + v \log(1 - u)}{uv} = \frac{\pi^2}{6} + \zeta_3 = c_1 \pi^2 + c_2 \zeta_3 = \vec{c} \cdot \vec{v}$$

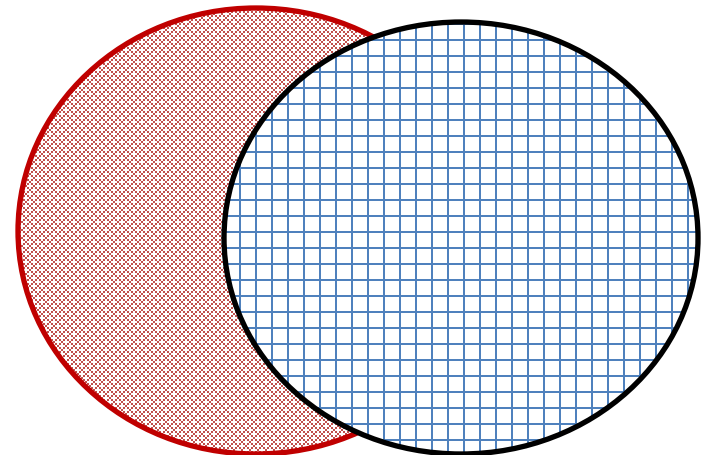
Q: how many digits of f are required to fit rational c_1 and c_2 ?

$$\vec{v} = (\pi^2, \zeta_3)$$

- Multiple solutions implies that $\vec{c} \cdot \vec{v} = 0$
- Multiply by GCD so c_1 and c_2 are integers
 - There are $(10^R)^n = 10^{2R}$ vectors (c_1, c_2)
- Assume d digits of precision on v
 - $\vec{c} \cdot \vec{v}$ produce $10^{2R} d$ digit numbers
- There are only 10^d d -digit numbers in all
- Need precision $d > nR$ to fit pure numbers
 - Information content must be sufficient

assume size of c 's

$$c_1 \sim c_2 \lesssim 10^R$$



Precision requirements

For fitting *functions* we can sample at multiple points

$$f(x) = G(0, 1; x) - G(1, -1; x) \quad x_1 = 4/10, x_2 = 9/10$$

$$\mathcal{B}(x) = \{G(1, 0; x), G(0, 1; x), G(0, -1; x), G(1, -1; x)\}$$

$$M = \text{round } 10^s \left(\begin{array}{c} f(\mathbf{x}_1) \cdots f(\mathbf{x}_p) \\ \mathcal{B}_1(\mathbf{x}_1) \cdots \mathcal{B}_1(\mathbf{x}_p) \\ \vdots \\ \mathcal{B}_n(\mathbf{x}_1) \cdots \mathcal{B}_n(\mathbf{x}_p) \end{array} \middle| 10^{-s} \mathbb{I}_{n+1} \right) = \begin{pmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \mathbf{v}_3 \\ \mathbf{v}_4 \\ \mathbf{v}_5 \end{pmatrix} = \begin{pmatrix} -35 & -24 & 1 & 0 & 0 & 0 & 0 \\ 92 & 154 & 0 & 1 & 0 & 0 & 0 \\ -45 & -129 & 0 & 0 & 1 & 0 & 0 \\ 36 & 75 & 0 & 0 & 0 & 1 & 0 \\ -10 & -106 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

- With p points and d digits
 - net digits of information is $p \times d$
- Expected digits needed

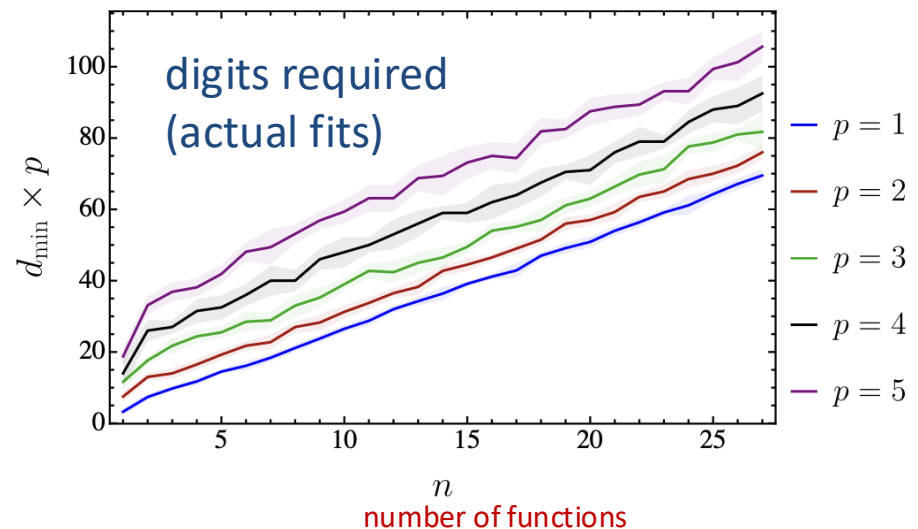
digits of precision req'd

basis functions

size of integers

number of points

$$d \lesssim \frac{nR}{p}$$

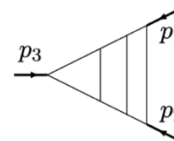
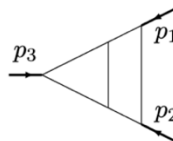
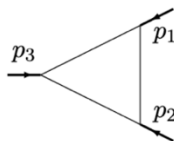


We can trade off digits of precision for number of points

- Will work even if only a few digits of precision are available!

Example 1: Triangles

Triangle ladder diagrams



$$z\bar{z} = p_2^2/p_1^2,$$

$$(1-z)(1-\bar{z}) = p_3^2/p_1^2$$

exact results known

$$T_1(z) = \frac{1}{z-\bar{z}} \left[2\text{Li}_2(z) - \text{Li}_2(\bar{z}) + \log(z\bar{z}) \log\left(\frac{1-z}{1-\bar{z}}\right) \right],$$

$$T_2(z) = \frac{1}{(1-z)(1-\bar{z})(z-\bar{z})} \left[6\text{Li}_4(z) - 6\text{Li}_4(\bar{z}) - 3\log(z\bar{z})(\text{Li}_3(z) - \text{Li}_3(\bar{z})) \right. \\ \left. + \frac{1}{2}\log^2(z\bar{z})(\text{Li}_2(z) - \text{Li}_2(\bar{z})) \right],$$

$$T_3(z) = \frac{1}{(1-z)^2(1-\bar{z})^2(z-\bar{z})} \left[20\text{Li}_6(z) - 20\text{Li}_6(\bar{z}) - 10\log(z\bar{z})(\text{Li}_5(z) - \text{Li}_5(\bar{z})) \right. \\ \left. + \log^2(z\bar{z})(\text{Li}_4(z) - \text{Li}_4(\bar{z})) - \frac{1}{6}\log^3(z\bar{z})(\text{Li}_3(z) - \text{Li}_3(\bar{z})) \right]$$

Full alphabet (from SOFIA)

$$A_{1,2} = \left\{ z\bar{z}, (1-z)(1-\bar{z}), z-\bar{z}, \frac{\bar{z}}{z}, \frac{1-z}{1-\bar{z}} \right\}$$

Simplified alphabet (quicker for testing)

$$A_3^* = \left\{ z\bar{z}, (1-z)(1-\bar{z}), \frac{\bar{z}}{z}, \frac{1-z}{1-\bar{z}} \right\}$$

Allow all possibilities up to weight 6

Weight-0: 1

Weight-1: $G(a_1, x)$, π

Weight-2: $G(a_1, a_2, x)$, $\pi \times G(a_1, x)$, ζ_2

Weight-3: $G(a_1, a_2, a_3, x)$, $\pi \times G(a_1, a_2, x)$, $\zeta_2 \times G(a_1, x)$, ζ_3

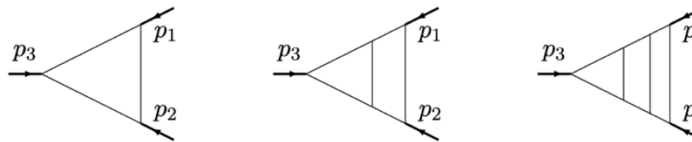
Weight-4: $G(a_1, a_2, a_3, a_4, x)$, $\pi \times G(a_1, a_2, a_3, x)$, $\zeta_2 \times G(a_1, a_2, x)$, $\pi^3 \times G(a_1, x)$, $\zeta_3 \times G(a_1, x)$, ζ_4

Weight-5: $G(a_1, a_2, a_3, a_4, a_5, x)$, $\pi \times G(a_1, a_2, a_3, a_4, x)$, $\zeta_2 \times G(a_1, a_2, a_3, x)$, $\pi^3 \times G(a_1, a_2, x)$, $\zeta_3 \times G(a_1, a_2, x)$, $\zeta_4 \times G(a_1, x)$, ζ_5 , $\zeta_2 \times \zeta_3$

Weight-6: $G(a_1, a_2, a_3, a_4, a_5, a_6, x)$, $\pi \times G(a_1, a_2, a_3, a_4, a_5, x)$, $\zeta_2 \times G(a_1, a_2, a_3, a_4, x)$, $\pi^3 \times G(a_1, a_2, a_3, x)$, $\zeta_3 \times G(a_1, a_2, a_3, x)$, $\zeta_4 \times G(a_1, a_2, x)$, $\zeta_5 \times G(a_1, x)$, $\zeta_2 \zeta_3 \times G(a_1, x)$, $\pi^5 \times G(a_1, x)$, ζ_6 , ζ_3^2

Example 1: Triangles

Triangle ladder diagrams



Pick random points in (unphysical) Euclidean region $0 < z < \bar{z} < 1$

- Makes basis functions real
- Imaginary numbers are fine, just technically complicated python implementation

Diagram	AMFlow point time	Transcendental weights	# points sampled	Basis size	Reduction time
One-loop	15.6 CPU-min	≤ 2	5	full(32)	<1s
				simplified(26)	<1s
				uniform(25)	<1s
Two-loop	1.1 CPU-h	≤ 4	100	full(488)	9.6 min
			100	simplified(393)	10.7 min
			60	uniform(366)	3.5 min
Three-loop	5.7 CPU-h	≤ 6	-	full(1373)	-
			-	simplified(972)	-
			200	uniform(806)	1.1 h

3 digits

20 digits

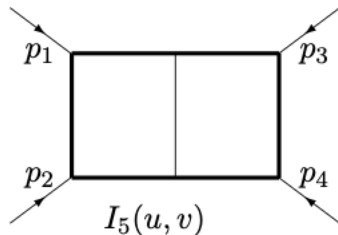
20 digits

Results with timing

- Rate limiting step is AMFlow (computation of full function)
- Could be sped up (additional points much faster than first)

Example 2: Double box

Loop



12 independent letters

$$\tilde{A} = \left\{ u, v, 1+u, 1+v, u+v, 1+u+v, \frac{\beta_u - 1}{\beta_u + 1}, \frac{\beta_v - 1}{\beta_v + 1}, \frac{\beta_{uv} - 1}{\beta_{uv} + 1}, \frac{\beta_{uv} - \beta_u}{\beta_{uv} + \beta_u}, \frac{\beta_{uv} - \beta_v}{\beta_{uv} + \beta_v}, \frac{\beta_{uv} - \beta_u \beta_v}{\beta_{uv} + \beta_u \beta_v} \right\}$$

$$\text{with } \beta_u = \sqrt{1+u}, \beta_v = \sqrt{1+v} \text{ and } \beta_{uv} = \sqrt{1+u+v}.$$

- $12^4 = 20,736$ weight-4 symbols + (?) lower weight terms
- square root letters are hard to integrate analytically

method 1:
rationalize the square roots

$$u = \frac{(1-w^2)(1-z^2)}{(w-z)^2} \quad \text{and} \quad v = \frac{4wz}{(w-z)^2},$$

$$\tilde{A}_2 = \{w, z, 1 \pm w, 1 \pm z, w \pm z, 1 \pm wz, 1 \pm w \mp z + wz\},$$

method 2:
numerically integrate along a contour

- integrate first and last symbol analytically
- need to be careful with branch cuts
 - euclidean region requires some thought
- using integrable contributions helps a lot

- Now symbols can be integrated analytically
 - Takes FiberSymbol hours to integrate
 - Result is hundreds or thousands of terms
- GiNaC can get numbers out, but very slow

Example 2: Double box

Landau
bootstrap

Analytic
regression

Easy

Constraints **# Coeffs**

Hard

relatively
easy

All Symbols	20736
Integrability	6993
Galois symmetry	861
Physical branch cuts	161
Genealogical constraints	28
α -positive thresholds	6

Hard

Easy



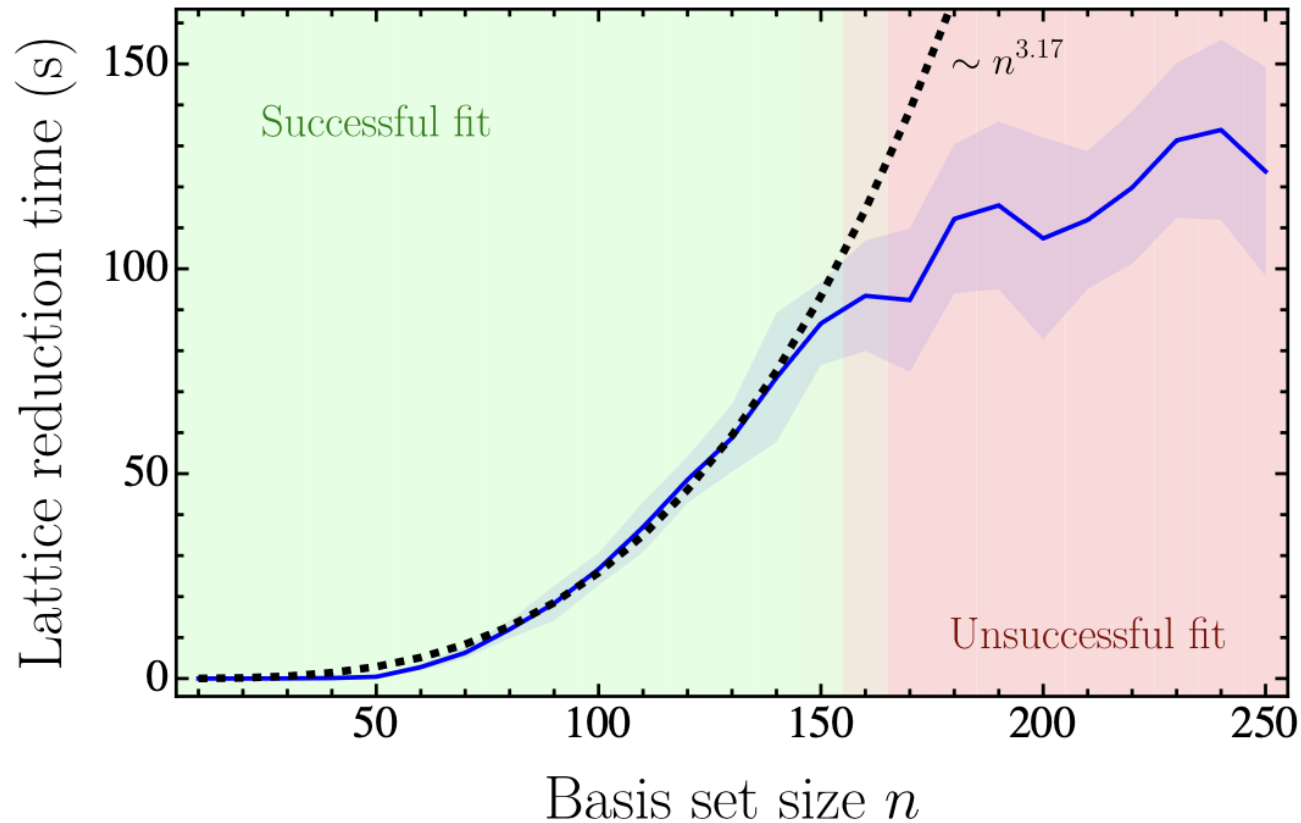
✓ 200pts 17 digits, $t \sim 30s$

✓ 200pts, 8 digits, $t < 1s$

✓ 200pts, 6 digits, $t < 1s$



Double box: limitations



Should work with more functions

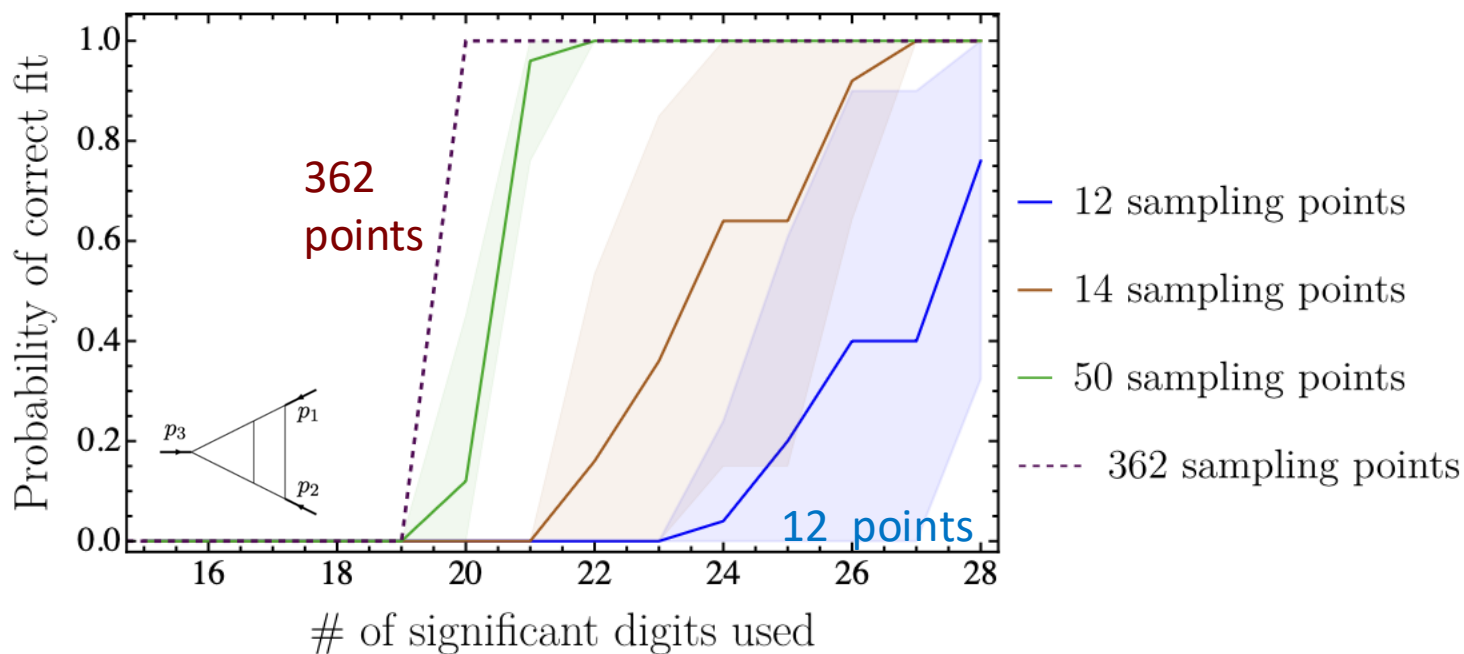
- With our compute, hard to succeed with more than $n \lesssim 200$

Choosing points

- Before we said you can get away with fewer digits if you use more points

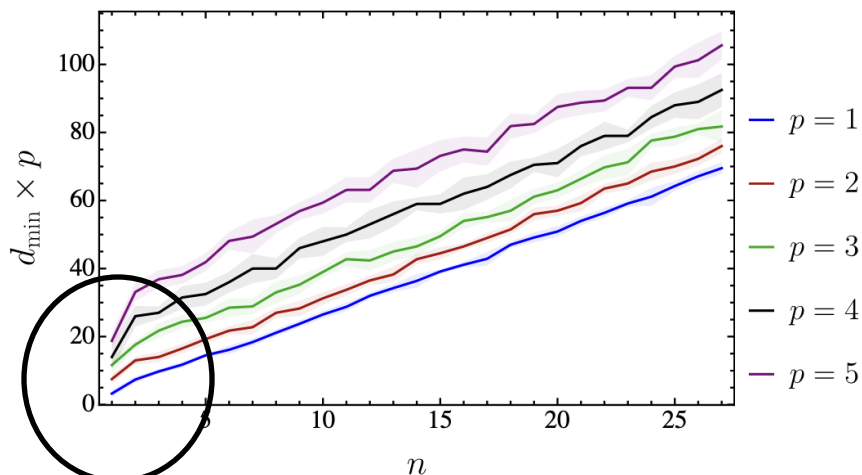
$$d \lesssim \frac{nR}{p}$$

basis functions \rightarrow n
 size of integers \rightarrow R
 digits of precision req'd \rightarrow d
 number of points \rightarrow p



- Can never succeed below some digit lower bound
- Why did scaling fail?

Choosing points



offset near $d=0$

$$d_{\min} \approx R_{\text{eff}} \frac{n}{p} + d_0$$

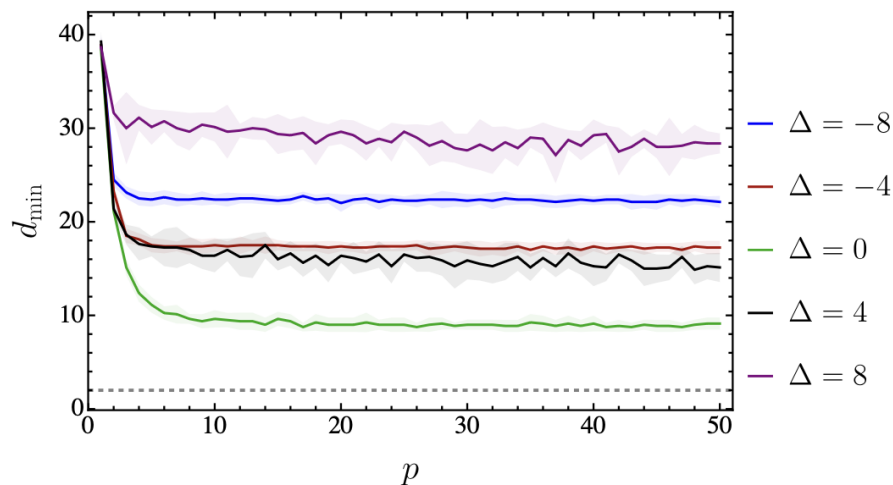
- will never work with 1 or 2 digits

$$f(p_j) = \{103.2, \underbrace{2.5, 2.3}_{\text{unrecoverable information loss if we truncate to 2 digits}}\}$$

unrecoverable information
loss if we truncate to 2 digits

choose points in a range

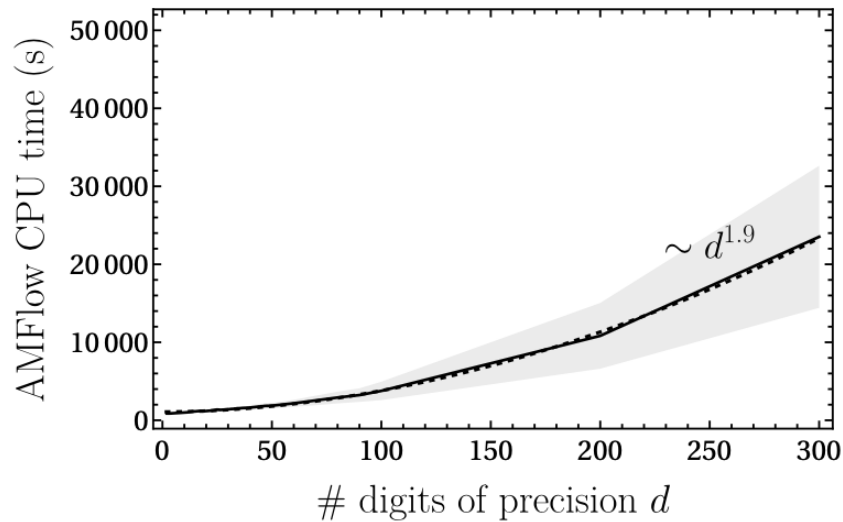
$$\frac{1}{2} - 10^\Delta \leq x \leq \frac{1}{2} + 10^\Delta$$



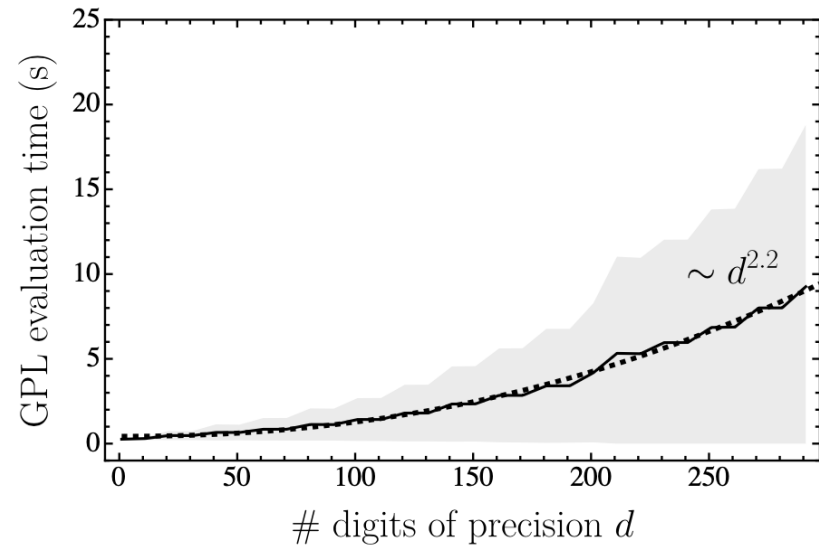
- want to choose points
 - not too close (lose information)
 - not too far (need more digits)
 - Need 10-20 digits at least

Double box: timing

AMFlow + Kira (for IBP)



GPL evaluation (GINSH)



$$t(p, n)/\text{ns} \approx \underbrace{10^9 \cdot p \cdot d_{\min}^2(n)}_{\text{AMFlow}} + \underbrace{10^4 \cdot n \cdot p \cdot d_{\min}^2(n)}_{\text{GINSH}} + \underbrace{p \cdot n^4}_{\text{fitting}},$$

- Trading digits for points makes scaling go from quadratic to linear!

Application to EECs

Consider some types of energy-energy correlators (unequal energy weights)

$$\frac{d\sigma}{dx_{12} \cdots dx_{(N-1)N}} \equiv \sum_m \sum_{1 \leq i_1, \dots, i_N \leq m} \int d\sigma_m \times \prod_{1 \leq k \leq N} \frac{E_{i_k}}{Q} \prod_{1 \leq j < l \leq N} \delta \left(x_{jl} - \frac{1 - \cos \theta_{i_j i_l}}{2} \right).$$

Uses of lattice reduction

- Find linear dependence among basis functions

$$G(z) = D(z) + a_{0,11} g_1(z) + a_{0,12} g_2(z) + a_{1,12} g_3(z) + a_{2,12} g_4(z) + c_{1,12} g_5(z) + d_{2,12} g_6(z)$$

$$g_3(z) = \frac{1}{(z-1)^2 z^2 (\bar{z}-1)^2 \bar{z}^2} \left[z^4 \bar{z}^2 - z^4 \bar{z} + 8z^3 \bar{z}^3 - 14z^3 \bar{z}^2 + 8z^3 \bar{z} - z^3 + z^2 \bar{z}^4 - 14z^2 \bar{z}^3 \right. \\ + 24z^2 \bar{z}^2 - 14z^2 \bar{z} + z^2 + (2z^4 \bar{z}^3 - 3z^4 \bar{z}^2 + z^4 \bar{z} + 2z^3 \bar{z}^4 - 8z^3 \bar{z}^3 + 9z^3 \bar{z}^2 - 4z^3 \bar{z} + z^3 \\ - 3z^2 \bar{z}^4 + 9z^2 \bar{z}^3 - 12z^2 \bar{z}^2 + 9z^2 \bar{z} - 3z^2 + z \bar{z}^4 - 4z \bar{z}^3 + 9z \bar{z}^2 - 8z \bar{z} + 2z + \bar{z}^3 - 3\bar{z}^2 \\ + 2\bar{z}) \log((z-1)(\bar{z}-1)) + (-2z^4 \bar{z}^3 + 3z^4 \bar{z}^2 - z^4 \bar{z} - 2z^3 \bar{z}^4 + 8z^3 \bar{z}^3 - 9z^3 \bar{z}^2 + 2z^3 \bar{z} \\ \left. + 3z^2 \bar{z}^4 - 9z^2 \bar{z}^3 + 6z^2 \bar{z}^2 - z \bar{z}^4 + 2z \bar{z}^3) \log(z\bar{z}) - z \bar{z}^4 + 8z \bar{z}^3 - 14z \bar{z}^2 + 8z \bar{z} - \bar{z}^3 + \bar{z}^2 \right]$$

- Treat $\{g_i\}$ as transcendental basis and $a_{i,j}, b_{i,j}, c_{i,j}, d_{i,j}$ as coefficients to determine
- (1). Run lattice reduction among $\{g_i(z)\}$ to get a linear-independent basis $\{\tilde{g}_i(z)\}$
- (2). Run lattice reduction among both $G(z)$ and $\{\tilde{g}_i(z)\}$

In this case, 2 numerical points and 13 digits fix all six parameters

Pros and cons: Landau bootstrap

Landau bootstrap



- Can eliminate large swaths of symbols with physical constraints
- Don't need to do integrals
- Leads to new deep understanding in what amplitudes are
- Requires subtle understanding of singularities
 - Analytic structure of amplitudes
 - Branch points, euclidean regions
 - Algebraic geometry
- Rational prefactors not fixed by singularities alone
- Often still requires some integration at the end

Pros and cons: analytic regression

Analytic regression
with lattice reduction



- Easy to automate
- Can work for any functions
 - not just polylogs with symbols
 - elliptic polyarithms? no problem!
 - cross sections, EECs, etc.
- Can find linear dependencies
- Can trade digits of accuracy for points
 - Scaling $t \sim n^2$ or worse to $t \sim n$
- Becomes computationally challenging above $n \sim 200$
 - AMFlow scales like $(\# \text{ digits})^2$
 - lattice reduction scales like $(\# \text{ constants})^4$
- Minimum number of digits needed (~ 5 or 6)

$$f(\mathbf{x}_j) = \sum_{i=1}^n c_i \mathcal{B}_i(\mathbf{x}_j) \quad c_i \in \mathbb{Q}$$



problem
solved

Conclusions

Happy Birthday Symbol

